

MAP and ML Estimation

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Overview of Candy Bag Example

As described in slides by Russell and Norvig, for Chapter 20 of the 2nd edition:

- Five kinds of bags of candies.
 - 10% are h_1 : 100% cherry candies
 - 20% are h_2 : 75% cherry candies + 25% lime candies
 - 40% are h_3 : 50% cherry candies + 50% lime candies
 - 20% are h_4 : 25% cherry candies + 75% lime candies
 - 10% are h_5 : 100% lime candies
- Each bag has an infinite number of candies.
 - This way, the ratio of candy types does not change as we pick candies out of the bag.

Hypotheses and Observations

- We have a bag of a certain type, and we are picking candies out of that bag.
 - We don't know if our bag is of type 1, 2, 3, 4, or 5.
- We have five ***hypotheses***: h_1, h_2, h_3, h_4, h_5 .
- Out of the bag, we pick T candies, whose types are: Q_1, Q_2, \dots, Q_T .
 - Each Q_j is equal to either C (cherry) or L (“lime”).
 - These Q_j 's are called the ***observations***.

Questions We Want to Answer

- What is $P(h_i \mid Q_1, \dots, Q_t)$?
 - Probability of hypothesis i after t observations.
- What is $P(Q_{t+1} = C \mid Q_1, \dots, Q_t)$?
 - Similarly, what is $P(Q_{t+1} = L \mid Q_1, \dots, Q_t)$
 - Probability of observation $t+1$ after t observations.

Simplifying notation

- Define:
 - $P_t(h_i) = P(h_i \mid Q_1, \dots, Q_t)$
 - $P_t(Q_{t+1} = C) = P(Q_{t+1} = C \mid Q_1, \dots, Q_t)$?
- Special case: $t = 0$ (no observations):
 - $P_0(h_i) = P(h_i)$
 - $P_0(h_i)$ is the prior probability of h_i
 - $P_0(Q_1 = C) = P(Q_1 = C)$
 - $P_0(Q_1 = C)$ is the probability that the first observation is equal to C .

Questions We Want to Answer, Revisited

Using the simplified notation of the previous slide:

- What is $P_t(h_i)$?
 - Probability of hypothesis i after t observations.
- What is $P_t(Q_{t+1} = C)$?
 - Similarly, what is $P_t(Q_{t+1} = L)$
 - Probability of observation $t+1$ after t observations.

A Special Case of Bayes Rule

- In the solution, we will use the following special case of Bayes rule:
 - $P(A | B, C) = P(B | A, C) * P(A | C) / P(B | C)$.

Computing $P_t(h_i)$

- Let t be an integer between 1 and T :
- $P_t(h_i) = P(h_i | Q_1, \dots, Q_t) =$

$$\frac{P(Q_t | h_i, Q_1, \dots, Q_{t-1}) * P(h_i | Q_1, \dots, Q_{t-1})}{P(Q_t | Q_1, \dots, Q_{t-1})} \Rightarrow$$

$$\Rightarrow P_t(h_i) = \frac{P(Q_t | h_i) * P_{t-1}(h_i)}{P_{t-1}(Q_t)}$$

Computing $P_t(h_i)$ (continued)

- The formula
$$P_t(h_i) = \frac{P(Q_t | h_i) * P_{t-1}(h_i)}{P_{t-1}(Q_t)}$$
 is recursive, as it requires knowing $P_{t-1}(h_i)$. The base case is $P_0(h_i) = P(h_i)$.
- To compute $P_t(h_i)$ we also need $P_{t-1}(Q_t)$. We show how to compute that next.

Computing $P_{t+1}(Q_t)$

- $P_t(Q_{t+1}) = P(Q_{t+1} | Q_1, \dots, Q_t) =$
 $\sum_{i=1}^5 (P(Q_{t+1} | h_i) P(h_i | Q_1, \dots, Q_t)) \Rightarrow$

$$P_t(Q_{t+1}) = \sum_{i=1}^5 (P(Q_{t+1} | h_i) P_t(h_i))$$

Computing $P_t(h_i)$ and $P_t(Q_{t+1})$

- Base case: $t = 0$.
 - $P_0(h_i) = P(h_i)$, where $P(h_i)$ is known.
 - $P_0(Q_1) = \sum_{i=1}^5 (P(Q_1 | h_i) * P(h_i))$, where $P(Q_1 | h_i)$ is known.
- To compute $P_t(h_i)$ and $P_t(Q_{t+1})$:
- For $j = 1, \dots, t$
 - Compute $P_j(h_i) = \frac{P(Q_j | h_i) * P_{j-1}(h_i)}{P_{j-1}(Q_j)}$
 - Compute $P_j(Q_{j+1}) = \sum_{i=1}^5 (P(Q_{j+1} | h_i) * P_j(h_i))$

Computing $P_t(h_i)$ and $P_t(Q_{t+1})$

- Base case: $t = 0$.
 - $P_0(h_i) = P(h_i)$, where $P(h_i)$ is known.
 - $P_0(Q_1) = \sum_{i=1}^5 (P(Q_1 | h_i) * P(h_i))$, where $P(Q_1 | h_i)$ is known.
- To compute $P_t(h_i)$ and $P_t(Q_{t+1})$:
- For $j = 1, \dots, t$
 - Compute $P_j(h_i) = \frac{\overset{\text{known}}{P(Q_j | h_i)} * \overset{\text{computed at previous round}}{P_{j-1}(h_i)}}{\underset{\text{computed at previous round}}{P_{j-1}(Q_j)}}$
 - Compute $P_j(Q_{j+1}) = \sum_{i=1}^5 \left(\underset{\text{known}}{P(Q_{j+1} | h_i)} * \underset{\text{computed at previous line}}{P_j(h_i)} \right)$

MAP Estimate

- The Maximum a Posteriori (MAP) estimate answers the following question:
 - What is the most likely hypothesis given observations Q_1, \dots, Q_t ?
 - Answer:
 - Compute, for each h_i , $P_t(h_i)$, using the algorithm described in the previous slides.
 - Select the h_i with the highest value of $P_t(h_i)$. The winning h_i is called the *MAP estimate*.

ML Estimate

- The Maximum Likelihood (ML) estimate answers the following question:
 - What is the most likely hypothesis given observations Q_1, \dots, Q_t ?
 - Answer: Compute, for each h_i :
 - $P(Q_1, \dots, Q_t | h_i) = P(Q_1 | h_i) * \dots * P(Q_t | h_i)$
 - Select the h_i with the highest value of $P(Q_1, \dots, Q_t | h_i) P_t(h_i)$. The winning h_i is called the *ML estimate*.

Comparison of MAP and ML

- When there is enough information to compute both the MAP estimate and the ML estimate, then the MAP is more accurate, because it uses more information.
 - The ML estimate ignores the prior probabilities $P(h_i)$. Alternatively we can think that the ML estimate assumes that all prior probabilities $P(h_i)$ are equal to each other.
- When the prior probabilities $P(h_i)$ are not known, then only the ML estimate can be computed.
- Computing the ML estimate is more simple than computing the MAP estimate.